

**Department of Mathematics**  
**California State University, Los Angeles**  
**Master's Degree Comprehensive Examination in**

**NUMERICAL ANALYSIS**  
**Spring 2015**

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**Instructions:**

- Do exactly **two problems from Part A AND two problems from Part B**. If you attempt more than two problems in either Part A or Part B, and do not clearly indicate which two are to count, only the first two problems will be counted towards your grade.
  - No calculators, no cell phones and no electronic devices.
  - Closed books and closed notes.
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**Part A**

1. In this problem,  $A$  is the  $3 \times 3$  matrix given by

$$A = \begin{bmatrix} 2 & 1 & 1 \\ 4 & 3 & 3 \\ 8 & 7 & 9 \end{bmatrix}$$

- a. [6 points] Find the LU decomposition of  $A$ ; that is, find a unit lower triangular matrix  $L$  and an upper triangular matrix  $U$  such that  $A = LU$ .
- b. [3 points] **Use the result of part a** to find  $\det(A)$ .
- c. [3 points] If Gaussian elimination **with partial pivoting** were used to solve  $A\mathbf{x} = \mathbf{b}$ , where  $\mathbf{b}$  is an arbitrary 3-vector, what would be the first elementary row operation performed?
- d. [4 points] Give an example of a nonsingular  $2 \times 2$  matrix  $B$  for which an LU decomposition does not exist, **AND** explain why it does not exist.
- e. [9 points] For a general  $n \times n$  system of linear equations:
  - (i) Give one advantage of Gaussian elimination over an iterative method (such as Jacobi iteration) for solving it.
  - (ii) When solving it by Gaussian elimination, give one advantage of employing partial pivoting over *not* using partial pivoting.
  - (iii) Compare (do not calculate) the flop-counts of complete pivoting with that of partial pivoting.

2. a. [9 points] Suppose  $U$  is an arbitrary nonsingular upper triangular  $3 \times 3$  matrix; that is,  $u_{ij} = 0$  if  $i > j$ . Let  $G$  be the Gauss-Seidel iteration matrix for solving  $U\mathbf{x} = \mathbf{b}$  (where  $\mathbf{b}$  is an arbitrary 3-vector).
- Show that Gauss-Seidel iteration converges for this system by finding the spectral radius of  $G$ .
  - Find the rate of convergence of Gauss-Seidel iteration method on this system.
- b. [8+4 points] Now let  $U$  be the following specific  $3 \times 3$  upper triangular matrix and let  $\mathbf{b}$  be the following specific 3-vector:

$$U = \begin{bmatrix} 1 & 1 & 1 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{bmatrix}, \quad \mathbf{b} = \begin{bmatrix} 6 \\ 5 \\ 3 \end{bmatrix}$$

**Note that** the system  $U\mathbf{x} = \mathbf{b}$  has the solution  $[1 \ 2 \ 3]^T$ .

- Using the initial vector  $\mathbf{x}_0 = [1 \ 1 \ 1]^T$ , compute the third approximation to the solution,  $\mathbf{x}_3$ , by the Gauss-Seidel method.
  - Based on your answer to part **b(i)**, make a conjecture concerning what it means for an iterative method to have an infinite rate of convergence.
- c. [4 points] If we were to use Jacobi iteration to solve the system of part **b**, would we get the exact same iterates? Explain why or why not. (Do **not** actually solve that system using Jacobi iteration.)
3. Suppose that  $A$  is a symmetric nonsingular  $n \times n$  matrix with dominant eigenvalue  $\lambda_1$  ( $|\lambda_1| > |\lambda_k|$  for  $k = 2, 3, \dots, n$ ) and corresponding eigenvector  $\mathbf{v}_1$ .
- [6 points] Describe the Power Method algorithm for approximating the eigenvector  $\mathbf{v}_1$ . In what key way does this method differ from the Inverse Power Method?
  - [5 points] Explain how we use the approximation to  $\mathbf{v}_1$  of part **a**, call it  $\mathbf{x}^{(k)}$ , to obtain an approximation to the eigenvalue  $\lambda_1$ .
  - [5 points] Give the restriction on the initial vector  $\mathbf{x}^{(0)}$  that would ensure convergence of the Power Method under the conditions stated for this problem.
  - [6 points] Assuming that all conditions for convergence are satisfied, prove that the sequence of Power Method approximations  $\mathbf{x}^{(0)}, \mathbf{x}^{(1)}, \mathbf{x}^{(2)}, \mathbf{x}^{(3)}, \dots$ , given by  $\mathbf{x}^{(k)} = A\mathbf{x}^{(k-1)}$ , converges to the eigenvector  $\mathbf{v}_1$ .
  - [3 points] Provide one application of numerical linear algebra in which we would want to approximate the dominant eigenvalue of a matrix, but not be interested in the other eigenvalues of that matrix.

**Part B**

1. Consider the boundary value problem defined on a closed bounded domain  $D$ :

$$\begin{aligned} 2U_{xx} + U_{yy} &= 0 \text{ in } D \\ U(x, y) &= f(x, y) \text{ on the boundary of } D \end{aligned} \quad (1)$$

- a. [6 points] Show that if there is a solution to (1), it is unique.

For parts b-d, let  $D = \{(x, y) | 0 \leq x \leq 2, 0 \leq y \leq 3\}$  with boundary conditions

$$\begin{aligned} U(x, 0) &= 0, \quad U(x, 3) = 3, \\ U_x(0, y) &= U, \quad U(2, y) = y \end{aligned} \quad (2)$$

- b. [4 points] Write down the usual 5-point finite difference approximation to the PDE in (1).
- c. [10 points] Determine the system of linear equations that results from solving the PDE (1) with boundary conditions (2) using the usual 5-point scheme from part (b) with  $\Delta x = \Delta y = 1$ . Write your system in the matrix form  $A\mathbf{u} = \mathbf{b}$ .
- d. [5 points] Explain why the solution to the difference approximation in part (c) is unique.
2. a. [2 points each] Explain briefly (or give the definition) what it means for a finite difference approximation to a given initial-boundary value problem to be:
- (i) consistent
  - (ii) stable
  - (iii) convergent

- b. [5 points] Determine whether the difference scheme

$$\frac{u_{i-1,j-1} - u_{i,j-1} - u_{i+1,j} + u_{i,j}}{\Delta x \Delta t}$$

is a consistent approximation to  $U_{xt}$ . Justify your answer.

- c. Consider the following second-order PDE:

$$\begin{aligned} U_{xx} &= x^2 U_{tt} + U, \quad -\infty < x < \infty, t \geq 0 \\ U(x, 0) &= x, \quad -\infty < x < \infty \\ U_t(x, 0) &= 1, \quad -\infty < x < \infty \end{aligned} \quad (3)$$

- (i) [3 points] Find the value(s)  $(x, t)$  for which the PDE (3) is hyperbolic.
  - (ii) [7 points] Suppose the characteristic curves that passes through the points  $P(1,0)$  and  $Q(2,0)$  intersect at a point  $R(x_R, t_R)$ . Find the exact values of  $x_R$  and  $t_R$ .
  - (iii) [4 points] Write down an explicit finite difference scheme that is consistent with the PDE (3). You need not prove it is consistent.
3. Consider the initial boundary value problem (IBVP):

$$U_t = U_{xx}, \quad 0 \leq x \leq 1, t \geq 0 \quad (4)$$

$$\begin{aligned}
 U(x, 0) &= x(1-x), 0 \leq x \leq 1 \\
 U(0, t) &= U(1, t) = 0, t > 0
 \end{aligned}$$

- a. [8 points] Suppose we use the explicit scheme

$$\frac{u_{i,j+1} - u_{i,j}}{k} = \frac{u_{i-1,j} - 2u_{i,j} + u_{i+1,j}}{h^2}$$

to approximate the PDE (4) above. Use von Neumann analysis to derive the stability condition for the scheme.

- b. [4 points] Write down (do not prove) a consistent and unconditionally stable finite difference method that is of order  $\mathcal{O}(k^2, k^2)$  if there is any. If there is none, explain why.
- c. Suppose an approximation to the PDE (4) with  $r = k/h^2$  has the matrix form

$$A\mathbf{u}_{j+1} = I\mathbf{u}_j, \tag{5}$$

where  $\mathbf{u}_j = [u_{1,j}, u_{2,j}, \dots, u_{N,j}]^T$ ,  $I$  is the identity matrix and  $A$  is the tridiagonal matrix of order  $N-1$ :

$$A = \begin{pmatrix}
 1+2r & -r & 0 & 0 \\
 -r & 1+2r & -r & 0 \\
 0 & -r & 1+2r & -r \\
 0 & 0 & -r & \ddots
 \end{pmatrix}$$

- (i) [5 points] Write down the finite difference scheme given by the matrix equation (5). Is it an explicit or implicit scheme?
- (ii) [8 points] By computing the eigenvalues of the appropriate matrix, derive the condition for stability for the scheme.

